



Application Overview

- Total Hip and Knee Replacement Surgery
 - replace damaged articulating surfaces with implants
 - cemented use cement to attach to bone
 - · cementless rely on bone ingrowth
 - position/orientation is important
 - proper fit can be important (cementless)



Current Technique for THR

- Pre-operative planning using X-rays and acetate overlays
- Surgical preparation using mallet and broach or reamer
- Relies on surgeon's "feel"
- Outcome depends on surgeon experience

PLAY MOVIE

ROBODOC THR Procedure

- Pre-operative planning using 3-D CT scan data and implant models (ORTHODOC®)
- Surgical preparation of bone by robot using milling tool
 - Increased dimensional accuracy
 - Increased placement accuracy
- Outcome more consistent



ROBODOC Procedure Overview

- Perform orthopedic procedures (hip and knee replacement):
 - Preoperative CT scan
 - Preoperative planning
 - Intraoperative registration
 - Robotic machining of bone

ROBODOC Pin-Based Registration

- Surgery to implant pins (bone screws) prior to CT
- Planning software detects pins in CT coordinates
- Robot finds pins in Robot coordinates
- Software computes transformation between CT coordinates and robot coordinates
- Software uses transformation to convert planned implant position (CT coordinates) to surgical position of bone (Robot coordinates)

Pin-Based Registration

- Q: How many pins are needed?
- A: Need at least 3 "features"
 3 Pin Registration: uses center of each pin
 2 Pin Registration: uses center of each pin and axis of one pin

Pin-Based Registration

- + Easy to implement
- + Easy to use
- + Very accurate (if pins far enough away)
- + Very reliable
- Requires extra surgery
- Causes knee pain in many patients

ROBODOC Pinless Registration

- More complex (point-to-surface matching)
- Surgeon creates surface model of bone from preoperative CT (semi-automatic software).
- Surgeon uses digitizing device to collect bone surface points intraoperatively.
- Software ensures good distribution of points
- Surgeon verifies result

PLAY Pinless Video (1998)

ROBODOC Procedures

- Primary Total Hip Replacement (THR) - Pin-based and pinless
- Primary Total Knee Arthroplasty (TKA) - Pin-based and pinless
- Revision THR (cement removal) - Pin-based only

ROBODOC History



1986-1988 Feasibility study and proof of concept at U.C. Davis and IBM



May 2, 1990 First canine surgery











Commercial System Lessons

- Robot should either save time (money) or provide substantial clinical benefit (enable new procedures).
- Robot must interface with other devices in the operating room of the future.
- Registration should not require an additional surgery.
- Further size reduction is necessary.

ROBODOC Status

- Approximately 50 systems installed worldwide
 - Europe (Germany, Austria, Switz., France, Spain)
 - Asia (Japan, Korea, India)
 - U.S. (Clinical trial for FDA approval)
- Over 10,000 hip replacement surgeries
- Several hundred knee replacement surgeries

PLAY Total Knee Surgery Movie (2000)

Summary

- The ROBODOC System has evolved over the past 15+ years:
 - Laboratory prototype
 - Canine system
 - Clinical prototype
 - Commercial product

