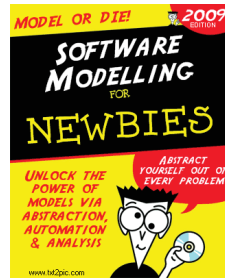


CISC836: Models in Software Development: Methods, Techniques and Tools



UML-RT and RSARTE: Part V

Juergen Dingel
February 2021

UML-RT

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UML-RT/RSARTE: Part V

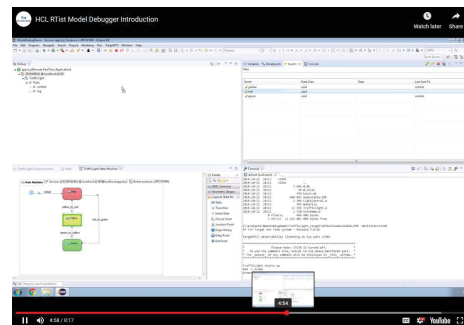
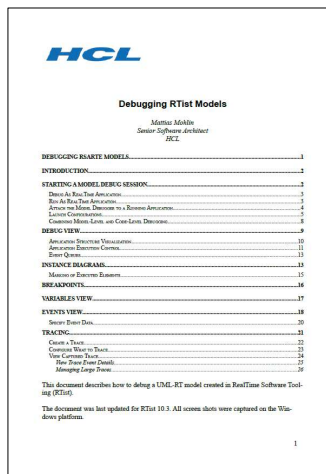
- Model debugger
- UML-RT: other features
 - Inheritance
 - Capsule, state machine
 - Synchronous calls
 - invoke vs send in `RTProtocol.h`
 - Message priorities
- Generating multi-threaded code
- Support for distributed, web-based systems

UML-RT

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Debugging in RSARTE



<https://www.youtube.com/embed/oeJgrMb3UU>

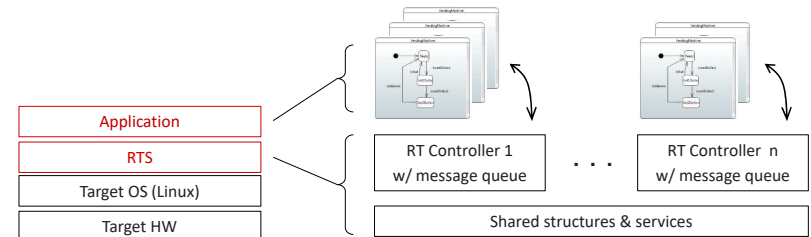
<https://rist.hcldoc.com/help/topic/com.ibm.xttools.rsarte.webdoc/pdf/RTist%20Model%20Debuq.pdf>

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Creating Multi-Threaded Applications



- Fixed capsule parts
 - instance always runs in the same thread as owning capsule instance
- Optional and plugin capsule parts
 - Instance can run in its own **physical thread**
- Each physical thread
 - has one **controller w/ its own message queue**, executing possibly many state machines

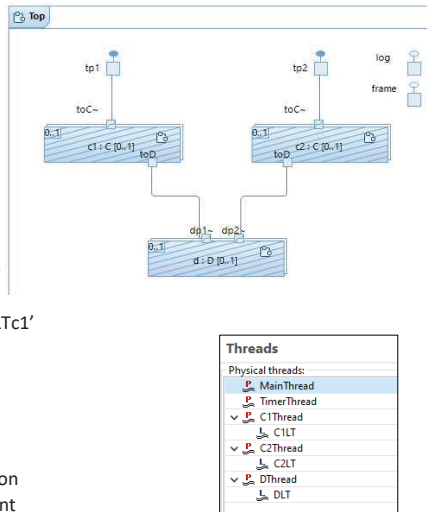
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Creating Multi-Threaded Applications (Cont'd)

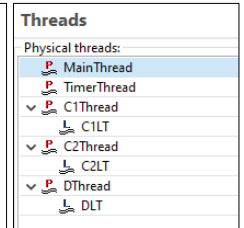
- **Logical thread**
 - Refers to the execution of a capsule instance/state machine
- To make the instance in optional capsule part c1 run in its own thread:
 - In **transformation configuration**:
 1. Create physical thread w/ some name, e.g., 'PTc1'
 2. Create logical thread w/ some name 'LTc1'
=> Code generator creates variable 'RTController LTc1'
 3. Assign LTc1 to PTc1
 - In **capsule owning c1**:
 1. when incarnating c1, use special version of **incarnate** with 'LTc1' as argument



Creating Multi-Threaded Applications (Cont'd)

▪ Example

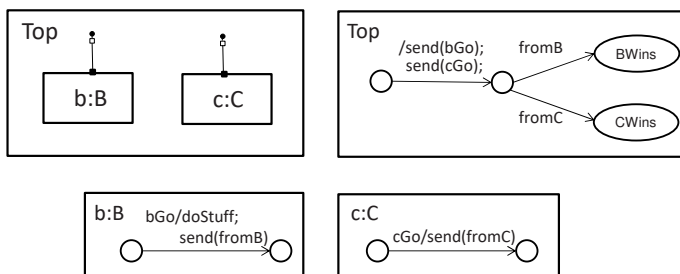
```
log.log("[Top] starting up");
RTTypedValue noData ( (const void *)0, (const RTObject_class *)0 );
log.log("[Top] incarnating part 'c1'");
RTActorId id1 = frame.incarnate(c1, noData, C1LT);
log.log("[Top] incarnating part 'c2'");
RTActorId id2 = frame.incarnate(c2, noData, C2LT);
log.log("[Top] incarnating part 'd'");
RTActorId id3 = frame.incarnate(d, noData, DLT);
log.log("[Top] sending 'go' to 'c1'");
tp1.go().send();
log.log("[Top] sending 'go' to 'c2'");
tp2.go().send();
```



▪ Incarnation w/ thread assignment

- **RTActorId incarnate (RTActorRef & cp, RTTypedValue & info, RTController * controller, int index)**
 - **info** is data to be passed into incarnated part
 - **controller** is controller which should run the incarnated part
 - **index** specifies where to insert part in case of replicated parts

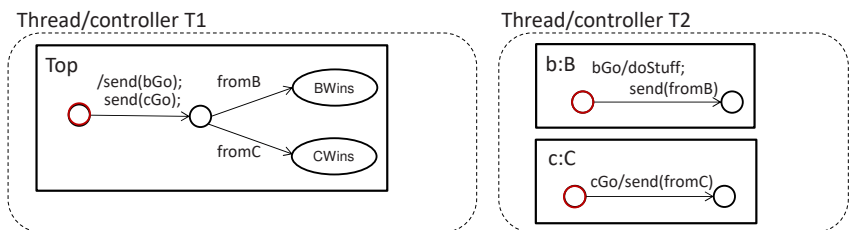
Impact of Multi-Threading (1/5)



- What if b and c execute on
 - the **same thread/controller** (and, thus, share a message queue)?
 - **different threads/controllers** (and, thus, have their own message queues)?
- What if 'doStuff' takes a really long time?
- What about 'run-to-completion'?

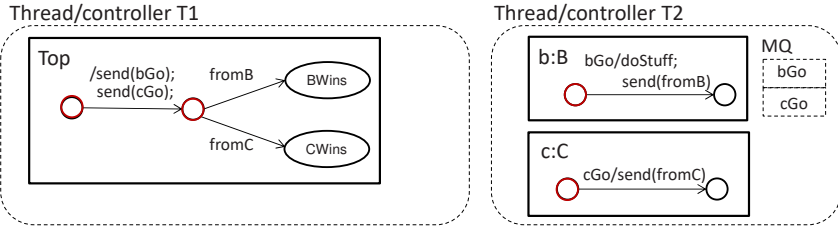
Impact of Multi-Threading (2/5)

b and c run on same thread



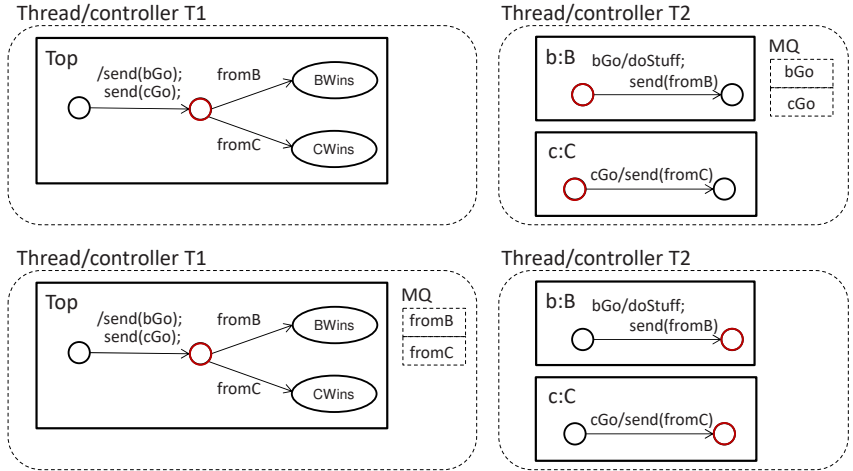
Impact of Multi-Threading (3/5)

b and c run on **same** thread



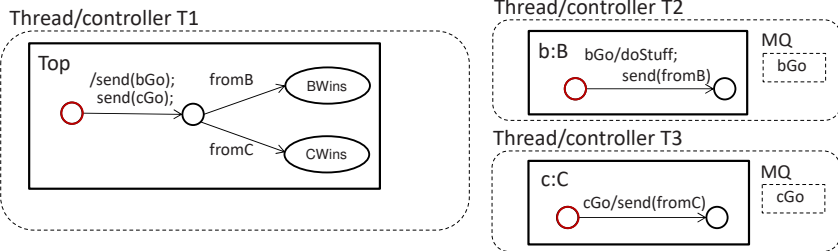
Impact of Multi-Threading (4/5)

b and c run on **same** thread



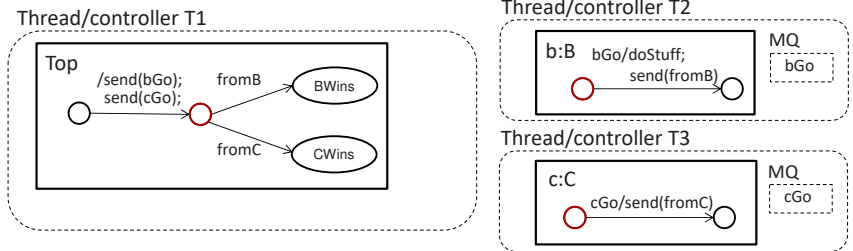
Impact of Multi-Threading (5/5)

b and c run on **different** threads



Impact of Multi-Threading (5/5)

b and c run on **different** threads



3 cases:

- if doStuff 'short', b always wins
- elsif doStuff 'long', c always wins
- else ?

Model available as sample model

```

$ ./executable.exe -URTS_DEBUG=quit -UARGS "different" 25000
[Top] sending 'go' to 'b' and then to 'c'; waiting to see who responds first
[c ] got 'go' from 'Top'[b ] got 'go' to 'Top', iterating now ...
[c ] sending 'fromC' to 'Top'[b ] ... done, sending 'fromB' to 'Top'
[Top] got 'fromC'
[Top] got 'fromB', 'c' wins

[Top] sending 'go' to 'b' and then to 'c'; waiting to see who responds first
[b ] got 'go' to 'Top', iterating now ...[c ] got 'go' from 'Top'
[b ] ... done, sending 'fromB' to 'Top'[c ] sending 'fromC' to 'Top'
[Top] got 'fromB'
[Top] got 'fromC', 'b' wins
    
```

Creating Multi-Threaded Applications (Cont'd)

■ Pros

- Make parts of application more independent
 - Long execution steps in one part will not reduce responsiveness of another
- If threads have priority
 - better performance for tasks on threads with higher priority
- If threads are mapped to cores
 - better performance for all tasks

■ Cons

- Multi-threading typically introduces the possibility for more than one transition to be enabled in a stable state configuration
 - ⇒ Correct design requires ensuring that messages arrive and are processed in correct order by several different controllers
- Multi-threading makes application more susceptible to
 - Specifics of platform (RTS/OS, hardware) and communication media
 - ⇒ Change in RTS, OS, C++ libraries, hardware, resource use can lead to messages being delivered and processed in different order
 - ⇒ Model must be carefully designed to make it robust to these changes