

# Decision Problems for Restricted Variants of Two-Dimensional Automata

CIAA 2019

Taylor J. Smith

Joint work with K. Salomaa

School of Computing  
Queen's University  
Kingston, Ontario, Canada

July 22, 2019

## Introduction

- Two-Dimensional Automata
- Restricted 2D Automata
- Decision Problems

## Language Emptiness

- Unary Three-Way Nondeterministic
- Two-Way Nondeterministic

## Language Equivalence

- Two-Way Deterministic

## Row/Column Projection

## Conclusions

## Introduction

Two-Dimensional Automata

Restricted 2D Automata

Decision Problems

## Language Emptiness

Unary Three-Way Nondeterministic

Two-Way Nondeterministic

## Language Equivalence

Two-Way Deterministic

## Row/Column Projection

## Conclusions

- ▶ A two-dimensional (2D) automaton is a generalization of a one-dimensional automaton.
- ▶ Two major differences:
  1. Different input word
  2. Different transition function

- ▶ A two-dimensional (2D) automaton is a generalization of a one-dimensional automaton.
- ▶ Two major differences:
  1. **Different input word**
  2. Different transition function

$$\begin{array}{cccccc} \# & \# & \# & \cdots & \# & \# \\ \# & a_{1,1} & a_{1,2} & \cdots & a_{1,n} & \# \\ \# & a_{2,1} & a_{2,2} & \cdots & a_{2,n} & \# \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ \# & a_{m,1} & a_{m,2} & \cdots & a_{m,n} & \# \\ \# & \# & \# & \cdots & \# & \# \end{array}$$

- ▶ A two-dimensional (2D) automaton is a generalization of a one-dimensional automaton.
- ▶ Two major differences:
  1. Different input word
  2. **Different transition function**

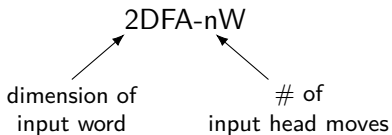
$$\delta : (Q \setminus q_{\text{accept}}) \times (\Sigma \cup \{\#\}) \rightarrow Q \times \{U, D, L, R\} \quad \delta : (Q \setminus q_{\text{accept}}) \times (\Sigma \cup \{\#\}) \rightarrow 2^{Q \times \{U, D, L, R\}}$$

Deterministic  
four-way  
(2DFA-4W)

Nondeterministic  
four-way  
(2NFA-4W)

## Remark

A note on notation. . .



Notation like "4DFA" is found in literature discussing  $2DFA-4W$ .

- ▶ 2D automata do not have to be four-way automata.
- ▶ Restrict the transition function to get:
  - ▶ Three-way (3W) automata:  $\{D, L, R\}$
  - ▶ Two-way (2W) automata:  $\{D, R\}$
- ▶ Three-way automata cannot return to a row after moving downward, but they can read symbols multiple times in a row.
- ▶ Two-way automata are “read-once”.
  - ▶ Similar to a one-way one-dimensional automaton.



	2DFA-4W	2NFA-4W	2DFA-3W	2NFA-3W	2DFA-2W	2NFA-2W
membership	✓	✓	✓	✓	✓	✓
emptiness	✗	✗	✓	✓	✓	✓
universality	✗	✗	✓	✗	✓	?
equivalence	✗	✗	?	✗	?	?

	2DFA-4W	2NFA-4W	2DFA-3W	2NFA-3W	2DFA-2W	2NFA-2W
membership	✓	✓	✓	✓	✓	✓
emptiness	✗	✗	✓	✓†	✓*	✓*
universality	✗	✗	✓	✗	✓	?
equivalence	✗	✗	?	✗	⊙	?

⊙: new decidability result

\*: new complexity bound over general alphabets

†: new complexity bound over unary alphabets

	2DFA-4W	2NFA-4W	2DFA-3W	2NFA-3W	2DFA-2W	2NFA-2W
membership	✓	✓	✓	✓	✓	✓
emptiness	✗	✗	✓	✓†	✓*	✓*
universality	✗	✗	✓	✗	✓	⊗
equivalence	✗	✗	?	✗	⊗	⊗

- : new decidability result
- \*: new complexity bound over general alphabets
- †: new complexity bound over unary alphabets
- ⊗: new decidability result, post-publication

## Introduction

Two-Dimensional Automata

Restricted 2D Automata

Decision Problems

## Language Emptiness

Unary Three-Way Nondeterministic

Two-Way Nondeterministic

## Language Equivalence

Two-Way Deterministic

## Row/Column Projection

## Conclusions

- ▶ Language emptiness asks: given an automaton  $\mathcal{A}$ , is  $L(\mathcal{A}) = \emptyset$ ?
- ▶ Known to be decidable for three-way 2D automata.
  - ▶ Also PSPACE-hard for general alphabets.
  - ▶ See Inoue/Takanami (1980) and Petersen (1995).
- ▶ Easily seen to be decidable for two-way 2D automata.
  - ▶ Simply guess an accepting computation.

- ▶ The emptiness problem for two-way 1D automata is NP-complete.
  - ▶ See Galil (1976).
- ▶ A unary two-way 1D automaton is a special case of a unary three-way 2D automaton.
  - ▶ The 2D problem is at least NP-hard.

## Theorem

The emptiness problem for unary 2NFA-3W is NP-complete.

## Proof Sketch

Given a unary 2NFA-3W automaton  $\mathcal{A}$ , replace all downward moves with “stay-in-place” moves. Call the new automaton  $\mathcal{A}'$ . Evidently,  $L(\mathcal{A}) = \emptyset$  iff  $L(\mathcal{A}') = \emptyset$ . This is equivalent to deciding emptiness for a unary two-way 1D automaton.

- ▶ The proof of decidability of emptiness for two-way nondeterministic 2D automata is also a proof that the problem is in NP.
- ▶ It is possible to improve this bound.

## Theorem

The emptiness problem for 2NFA-2W is in P.

## Proof Sketch

Via a reachability procedure.

If  $q_{\text{accept}}$  is reachable, then the language is not empty. Given a 2NFA-2W automaton  $\mathcal{A}$  with  $n$  states, we can check reachability in polynomial time without nondeterminism.

- ▶ The proof of decidability of emptiness for two-way nondeterministic 2D automata is also a proof that the problem is in NP.
- ▶ It is possible to improve this bound.

## Corollary

The emptiness problem for 2DFA-2W is in P.



## Introduction

Two-Dimensional Automata

Restricted 2D Automata

Decision Problems

## Language Emptiness

Unary Three-Way Nondeterministic

Two-Way Nondeterministic

## Language Equivalence

Two-Way Deterministic

## Row/Column Projection

## Conclusions

- ▶ Language equivalence asks: given two automata  $\mathcal{A}$  and  $\mathcal{B}$ , is  $L(\mathcal{A}) = L(\mathcal{B})$ ?
- ▶ Known to be undecidable for four-way 2D automata.
  - ▶ See Blum/Hewitt (1967).
- ▶ Known to be undecidable for three-way nondeterministic 2D automata.
  - ▶ See Inoue/Takanami (1980).
- ▶ Unknown if decidable for three-way deterministic 2D automata.

- ▶ What about two-way 2D automata?
  - ▶ Seems like it should be decidable.
  - ▶ The argument is not very straightforward, though.

## Theorem

The equivalence problem for 2DFA-2W is decidable.

## Proof Sketch

Via a technical lemma.

## Lemma

Let  $\mathcal{A}$  and  $\mathcal{B}$  be 2DFA-2W with  $m$  and  $n$  states, respectively.

Denote  $z = m \cdot n \cdot |\Sigma|^2 + 1$  and  $f(z) = z^2 \cdot (z^2 + z - 1)$ .

If  $L(\mathcal{A}) - L(\mathcal{B}) \neq \emptyset$ , then  $L(\mathcal{A}) - L(\mathcal{B})$  contains a 2D word with at most  $f(z)$  rows and  $f(z)$  columns.

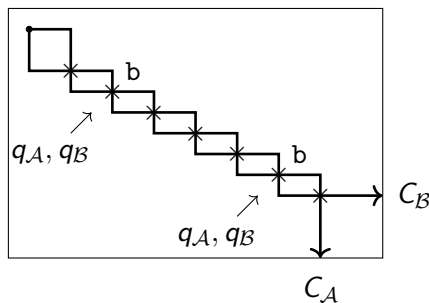
- ▶ In what follows, assume we have a word  $W \in L(\mathcal{A}) - L(\mathcal{B})$ .
- ▶ Intuitively speaking:
  - ▶ Suppose  $\mathcal{A}$  has an accepting computation  $C_{\mathcal{A}}$  on  $W$ .
  - ▶ Suppose  $\mathcal{B}$  has a rejecting computation  $C_{\mathcal{B}}$  on  $W$ .
  - ▶ The lemma uses a pumping property to reduce the dimension of  $W$  by removing shared states of  $C_{\mathcal{A}}$  and  $C_{\mathcal{B}}$ .
  - ▶ This gives a witness word of bounded dimension separating  $L(\mathcal{A})$  and  $L(\mathcal{B})$ .

## Proof Sketch

**Case 1:**  $C_A$  and  $C_B$  share at least  $z$  positions.

At least two of these shared positions must have been reached from the same states of  $\mathcal{A}$  and  $\mathcal{B}$  on the same symbol.

We can reduce dimension by identifying/removing these positions.



## Proof Sketch (cont'd)

**Case 2:**  $C_A$  and  $C_B$  share fewer than  $z$  positions.

There exists some subword  $Z$  consisting of  $z \cdot (z^2 + z - 1)$  consecutive complete columns of the input word where  $C_A$  and  $C_B$  do not intersect.

## Proof Sketch (cont'd)

**Case 2:**  $C_A$  and  $C_B$  share fewer than  $z$  positions.

There exists some subword  $Z$  consisting of  $z \cdot (z^2 + z - 1)$  consecutive complete columns of the input word where  $C_A$  and  $C_B$  do not intersect.

**Case 2(a):** One or both of  $C_A$  and  $C_B$  do not enter  $Z$ .

We can reduce dimension without affecting  $C_A$  or  $C_B$ .

## Proof Sketch (cont'd)

**Case 2:**  $C_A$  and  $C_B$  share fewer than  $z$  positions.

There exists some subword  $Z$  consisting of  $z \cdot (z^2 + z - 1)$  consecutive complete columns of the input word where  $C_A$  and  $C_B$  do not intersect.

**Case 2(b):** Both  $C_A$  and  $C_B$  enter  $Z$  without visiting all columns. Assume that  $C_A$  is above  $C_B$  and that  $C_A$  continues to the last row of  $Z$ .

We can reduce the columns without affecting  $C_A$  and  $C_B$ .



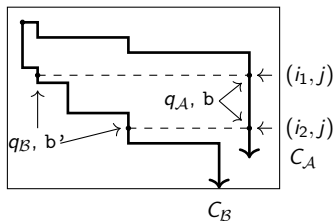
## Proof Sketch (cont'd)

**Case 2:**  $C_A$  and  $C_B$  share fewer than  $z$  positions.

There exists some subword  $Z$  consisting of  $z \cdot (z^2 + z - 1)$  consecutive complete columns of the input word where  $C_A$  and  $C_B$  do not intersect.

**Case 2(c):**  $C_A$  has a vertical drop of  $z$  steps within  $Z$ , or  $C_A$  finishes computation at least  $z$  positions higher than  $C_B$ .

We can reduce the rows without affecting  $C_A$  and  $C_B$ .



## Proof Sketch (cont'd)

At this point, we know that:

- ▶  $C_A$  is above  $C_B$  within  $Z$ ; and
- ▶ the vertical distance between each computation at the end is at most  $z$ .

Let  $\max_Z$  denote the maximal vertical difference of  $C_A$  and  $C_B$  at any fixed column in  $Z$ .

## Proof Sketch (cont'd)

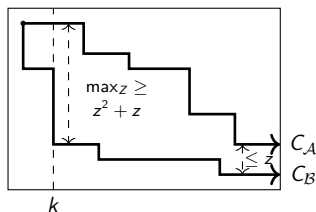
**Case 2(c)(i):** Assume  $\max_Z \geq z^2 + z$ .

Suppose the leftmost column of maximal vertical distance is  $k$ .

There must exist  $z$  columns between  $k$  and the last column of  $Z$  where vertical distance monotonically decreases or stays the same.

In two of these columns, the states of  $C_A$  and  $C_B$  and corresponding alphabet symbols coincide.

We can reduce the columns without affecting  $C_A$  or  $C_B$ .



## Proof Sketch (cont'd)

**Case 2(c)(ii):** Assume  $\max_Z \leq z^2 + z - 1$ .

Since  $Z$  consists of  $z \cdot (z^2 + z - 1)$  columns, there must exist  $z$  columns within  $Z$  where vertical distance stays the same.

In two of these columns, the states of  $C_A$  and  $C_B$  and corresponding alphabet symbols coincide.

We can reduce the columns without affecting  $C_A$  or  $C_B$ .

- ▶ The previous cases give a method to reduce the columns of the input word.
- ▶ The method to reduce rows is analogous.
- ▶ Altogether, the lemma gives a brute-force algorithm to decide equivalence by focusing only on input words up to a given dimension.

## Benefits of Approach

- ▶ The same argument also works for the inclusion problem.
  - ▶ The inclusion problem is therefore decidable for 2DFA-2W.

## Detriments of Approach

- ▶ The algorithm given by the technical lemma is inefficient.
- ▶ The same argument cannot be used for 2DFA-3W.

## Introduction

- Two-Dimensional Automata
- Restricted 2D Automata
- Decision Problems

## Language Emptiness

- Unary Three-Way Nondeterministic
- Two-Way Nondeterministic

## Language Equivalence

- Two-Way Deterministic

## Row/Column Projection

## Conclusions

- ▶ Row/column projections are operations on 2D words.
- ▶ The row (resp., column) projection of a 2D language  $L$  is the 1D language consisting of all first rows (resp., columns) of 2D words in  $L$ .

#	#	#	#	#
#	1	0	1	#
#	0	1	0	#
#	1	1	1	#
#	0	0	0	#
#	#	#	#	#

↓ (row proj.)

#	1	0	1	#
---	---	---	---	---



- ▶ Row/column projections over four-way 2D automata do not always produce regular languages.
  - ▶ This model can recognize words of dimension  $2^n \times 2^n$ .
  - ▶ Doesn't work even for a unary alphabet.
- ▶ What about three-way/two-way 2D automata?
  - ▶ These models cannot recognize exponential-dimension words.

## Theorem

The row projection language  $L(\mathcal{A})$  of a unary 2NFA-3W  $\mathcal{A}$  is regular.

## Proof Sketch

Replace downward moves with “stay-in-place” moves, as mentioned earlier.

## Theorem

The column projection language  $L(\mathcal{A})$  of a unary 2DFA-3W  $\mathcal{A}$  is not always regular.

## Proof Sketch

Construct a unary 2DFA-3W whose language is equal to

$$L_{\text{composite}} = \{a^m \mid m > 1 \text{ and } m \text{ is not prime}\}.$$

## Theorem

The row projection language  $L(\mathcal{A})$  of a general-alphabet 2NFA-2W  $\mathcal{A}$  is regular.

## Proof Sketch

Construct a one-way nondeterministic 1D automaton  $\mathcal{B}$  with “stay-in-place” moves to simulate the computation of  $\mathcal{A}$ .

$\mathcal{B}$  nondeterministically guesses symbols that  $\mathcal{A}$  reads when it moves downward and rightward.

$\mathcal{B}$  measures the number of rightward moves it made and the length of remaining input, and checks if there exists a matching accepting computation of  $\mathcal{A}$ .

## Corollary

The column projection language  $L(\mathcal{A})$  of a general-alphabet 2NFA-2W  $\mathcal{A}$  is regular.

	2DFA-4W	2NFA-4W	2DFA-3W	2NFA-3W	2DFA-2W	2NFA-2W
row projection	X	X	✓*	✓*	✓	✓
column projection	X	X	X	X	✓	✓

✓: always regular

X: sometimes non-regular

\*: unary alphabets only

## Introduction

- Two-Dimensional Automata
- Restricted 2D Automata
- Decision Problems

## Language Emptiness

- Unary Three-Way Nondeterministic
- Two-Way Nondeterministic

## Language Equivalence

- Two-Way Deterministic

## Row/Column Projection

## Conclusions

- ▶ 2D automata can be restricted to move in fewer than four directions.
- ▶ This restriction brings about interesting decidability properties.
- ▶ Language emptiness is NP-complete for unary 2NFA-3W.
- ▶ Language emptiness is in P for 2DFA-2W/2NFA-2W.
- ▶ Language equivalence is decidable for 2DFA-2W.
- ▶ Row projections are always regular over unary three-way 2D automata.
- ▶ Row/column projections are always regular over two-way 2D automata.



- ▶ For general-alphabet three-way 2D automata, is the emptiness problem in PSPACE?
- ▶ Does there exist an efficient algorithm to decide equivalence for 2DFA-2W?
- ▶ Is the equivalence problem decidable for 2DFA-3W?
- ▶ What else can we study about restricted 2D automaton models?

- [1] M. Blum and C. Hewitt. Automata on a 2-dimensional tape. In R. E. Miller, editor, *Proc. of SWAT 1967*, pages 155–160, 1967.
- [2] Z. Galil. Hierarchies of complete problems. *Acta Inf.*, 6(1):77–88, 1976.
- [3] K. Inoue and I. Takanami. A note on decision problems for three-way two-dimensional finite automata. *Inf. Proc. Lett.*, 10(4–5):245–248, 1980.
- [4] H. Petersen. Some results concerning two-dimensional Turing machines and finite automata. In H. Reichel, editor, *Proc. of FCT 1995*, volume 965 of *LNCS*, pages 374–382, Berlin Heidelberg, 1995. Springer-Verlag.
- [5] T. J. Smith and K. Salomaa. Decision problems for restricted variants of two-dimensional automata. In M. Hospodár and G. Jirásková, editors, *Proc. of CIAA 2019*, volume 11601 of *LNCS*, pages 222–234, Berlin Heidelberg, 2019. Springer-Verlag.