

# Concatenation Operations and Restricted Variants of Two-Dimensional Automata

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## Introduction

- Two-Dimensional Automata
- Restricted 2D Automata
- Concatenation Operations

## Row/Column Concatenation

- Two-Way 2D Automata
- Unary Two-Way 2D Automata

## Diagonal Concatenation

- Two-Way 2D Automata
- Three-Way 2D Automata

## Conclusions

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- ▶ A two-dimensional (2D) automaton is a generalization of a one-dimensional automaton.
- ▶ Two major differences:
  1. Different input word
  2. Different transition function

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- ▶ Two major differences:
  1. **Different input word**
  2. Different transition function

$$\begin{array}{cccccc} \# & \# & \# & \cdots & \# & \# \\ \# & a_{1,1} & a_{1,2} & \cdots & a_{1,n} & \# \\ \# & a_{2,1} & a_{2,2} & \cdots & a_{2,n} & \# \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ \# & a_{m,1} & a_{m,2} & \cdots & a_{m,n} & \# \\ \# & \# & \# & \cdots & \# & \# \end{array}$$

- ▶ A two-dimensional (2D) automaton is a generalization of a one-dimensional automaton.
- ▶ Two major differences:
  1. Different input word
  2. **Different transition function**

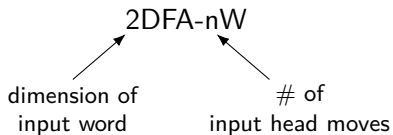
$$\delta : (Q \setminus q_{\text{accept}}) \times (\Sigma \cup \{\#\}) \rightarrow Q \times \{U, D, L, R\} \quad \delta : (Q \setminus q_{\text{accept}}) \times (\Sigma \cup \{\#\}) \rightarrow 2^{Q \times \{U, D, L, R\}}$$

Deterministic  
four-way  
(2DFA-4W)

Nondeterministic  
four-way  
(2NFA-4W)

## Remark

A note on notation. . .



Notation like “4DFA” is found in literature discussing  $2\text{DFA-}4\text{W}$ .

- ▶ 2D automata do not have to be four-way automata.
- ▶ Restrict the transition function to get:
  - ▶ Three-way (3W) automata:  $\{D, L, R\}$
  - ▶ Two-way (2W) automata:  $\{D, R\}$
- ▶ Three-way automata cannot return to a row after moving downward, but they can read symbols multiple times in a row.
- ▶ Two-way automata are “read-once”.
  - ▶ Similar to a one-way one-dimensional automaton.



- ▶ In two dimensions, we can concatenate two words  $w$  and  $v$ :
  - ▶ row-wise ( $w \ominus v$ )
  - ▶ column-wise ( $w \oplus v$ )

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$$w \ominus v = \begin{array}{cccc} \# & \# & & \# & \# \\ \# & w_{1,1} & \cdots & w_{1,n} & \# \\ & & \vdots & \ddots & \vdots \\ \# & w_{m,1} & \cdots & w_{m,n} & \# \\ \# & v_{1,1} & \cdots & v_{1,n} & \# \\ & & \vdots & \ddots & \vdots \\ \# & v_{m',1} & \cdots & v_{m',n} & \# \\ \# & \# & & \# & \# \end{array}$$

- ▶ In two dimensions, we can concatenate two words  $w$  and  $v$ :
  - ▶ row-wise ( $w \ominus v$ )
  - ▶ **column-wise** ( $w \oplus v$ )

$$w \oplus v = \begin{array}{cccccc} \# & \# & & \# & \# & & \# & \# \\ \# & w_{1,1} & \cdots & w_{1,n} & v_{1,1} & \cdots & v_{1,n'} & \# \\ & \vdots & \ddots & \vdots & \vdots & \ddots & \vdots & \\ \# & w_{m,1} & \cdots & w_{m,n} & v_{m,1} & \cdots & v_{m,n'} & \# \\ \# & \# & & \# & \# & & \# & \# \end{array}$$

- ▶ In two dimensions, we can concatenate two words  $w$  and  $v$ :
  - ▶ row-wise ( $w \ominus v$ )
  - ▶ column-wise ( $w \oplus v$ )
- ▶ Anselmo et al. (2005) introduced a third operation called **diagonal concatenation** ( $w \otimes v$ ).

$$w \otimes v = \begin{array}{cccccccc}
 \# & \# & & \# & \# & & \# & \# \\
 \# & w_{1,1} & \cdots & w_{1,n} & x_{1,1} & \cdots & x_{1,n'} & \# \\
 & \vdots & & \vdots & \vdots & & \vdots & \\
 \# & w_{m,1} & \cdots & w_{m,n} & x_{m,1} & \cdots & x_{m,n'} & \# \\
 \# & y_{1,1} & \cdots & y_{1,n} & v_{1,1} & \cdots & v_{1,n'} & \# \\
 & \vdots & & \vdots & \vdots & & \vdots & \\
 \# & y_{m',1} & \cdots & y_{m',n} & v_{m',1} & \cdots & v_{m',n'} & \# \\
 \# & \# & & \# & \# & & \# & \#
 \end{array}$$

- ▶ In two dimensions, we can concatenate two words  $w$  and  $v$ :
  - ▶ row-wise ( $w \oplus v$ )
  - ▶ column-wise ( $w \odot v$ )
- ▶ Anselmo et al. (2005) introduced a third operation called diagonal concatenation ( $w \otimes v$ ).
- ▶ Concatenation can be extended to languages in the usual way.

$$A \circ B = \{a \circ b \mid a \in A \text{ and } b \in B\}$$

	Row ( $\oplus$ )	Column ( $\oplus$ )	Diagonal ( $\otimes$ )
2DFA-4W	X	X	?
2NFA-4W	X	X	?
2DFA-3W	X	X	?
2NFA-3W	✓	X	?
2DFA-2W	?	?	?
2NFA-2W	?	?	?

	Row ( $\ominus$ )	Column ( $\oplus$ )	Diagonal ( $\oslash$ )
2DFA-4W	X	X	?
2NFA-4W	X	X	?
2DFA-3W	X	X	?
2NFA-3W	✓	X	?
2DFA-2W	⊗	⊗	?
2NFA-2W	⊗ / ✓ <sup>†</sup>	⊗ / ✓ <sup>†</sup>	?

†: applies to unary alphabets

	Row ( $\ominus$ )	Column ( $\oplus$ )	Diagonal ( $\oslash$ )
2DFA-4W	X	X	?
2NFA-4W	X	X	?
2DFA-3W	X	X	X
2NFA-3W	✓	X	?
2DFA-2W	X	X	X
2NFA-2W	X / ✓ <sup>†</sup>	X / ✓ <sup>†</sup>	✓

†: applies to unary alphabets



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## Theorem

The class 2NFA-2W is not closed under row concatenation.

## Proof (not in paper)

Let  $\Sigma = \{0, 1\}$ , and define  $L = \{w \mid \text{for all } j, w[1, j] = 0\}$ .

$L$  is recognized by a two-way 2D automaton.

An automaton recognizing  $L \oplus L$  accepts

$$\begin{array}{cc} 0 & 0 \\ 0 & 0 \end{array} \in L \oplus L.$$

But the accepting computation does not visit all symbols, so (for instance) the automaton may also accept

$$\begin{array}{cc} 0 & 0 \\ 1 & 0 \end{array} \notin L \oplus L.$$

## Theorem

The class 2NFA-2W is not closed under row concatenation.

- ▶ Adapting this to the deterministic case, we get. . .

## Corollary

The class 2DFA-2W is not closed under row concatenation.

- ▶ And, following a similar proof, we get. . .

## Corollary

The classes 2DFA-2W and 2NFA-2W are not closed under column concatenation.

- ▶ Before we proceed, we must modify our model slightly.
- ▶ An automaton  $\mathcal{A}$  is “IBR-accepting” if, upon reading a boundary marker on the bottom/right border of the word,  $\mathcal{A}$  immediately halts and accepts if it can reach  $q_{\text{accept}}$  from its current state.

## Lemma

Given a two-way 2D automaton  $\mathcal{A}$ , there exists an equivalent IBR-accepting two-way 2D automaton  $\mathcal{A}'$ .

## Theorem

The class 2NFA-2W over a unary alphabet is closed under row concatenation.

## Proof Sketch

We take a case-based approach.

- ▶ Let  $\mathcal{A}$  and  $\mathcal{B}$  be IBR-accepting unary two-way 2D automata.
- ▶ Automaton  $\mathcal{A}$  recognizes language  $A$  (and  $\mathcal{B}$  recognizes  $B$ ).
- ▶ Their accepting computations are denoted by  $C_{\mathcal{A}}$  and  $C_{\mathcal{B}}$ .

## Proof Sketch (cont'd)

We construct an automaton  $\mathcal{M}$  to recognize  $A \oplus B$ .

$\mathcal{M}$  nondeterministically chooses which “types” of computation correspond to  $C_A$  and  $C_B$ , and interleaves.

## “Types” of Computation

1.  $C_A$  accepts at bottom,  $C_B$  accepts at right
2.  $C_A$  accepts at right,  $C_B$  accepts at bottom
3. (a)  $C_A$  accepts at bottom in column  $i$ ,  $C_B$  accepts at bottom in column  $j < i$   
(b)  $C_A$  accepts at bottom in column  $i$ ,  $C_B$  accepts at bottom in column  $k \geq i$
4.  $C_A$  and  $C_B$  both accept at right

## Proof Sketch (cont'd)

1.  $C_A$  accepts at bottom,  $C_B$  accepts at right

We divide the computation of  $\mathcal{M}$  into two phases.

### First Phase

- (i) Simulate downward moves of  $\mathcal{A}$  by moving input head and changing state
- (ii) Simulate downward moves of  $\mathcal{B}$  by moving input head and changing state
- (iii) Simulate rightward moves of  $\mathcal{A}$  and  $\mathcal{B}$  by moving input head and changing state simultaneously

After completing step (iii), return to step (i) and repeat.

## Proof Sketch (cont'd)

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We divide the computation of  $\mathcal{M}$  into two phases.

### First Phase

- (i) Simulate downward moves of  $\mathcal{A}$  by moving input head and changing state
  - (ii) Simulate downward moves of  $\mathcal{B}$  by moving input head and changing state
  - (iii) Simulate rightward moves of  $\mathcal{A}$  and  $\mathcal{B}$  by moving input head and changing state simultaneously
- ▶ In step (i),  $\mathcal{M}$  can guess nondeterministically that the input head of  $\mathcal{A}$  is at the bottom border.
  - ▶ If  $\mathcal{A}$  is in an accepting state,  $\mathcal{M}$  moves to the second phase.



## Proof Sketch (cont'd)

1.  $C_A$  accepts at bottom,  $C_B$  accepts at right

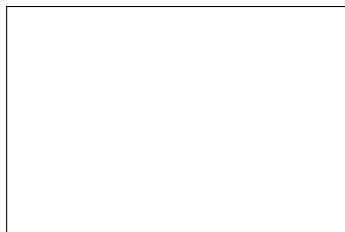
We divide the computation of  $\mathcal{M}$  into two phases.

## Second Phase

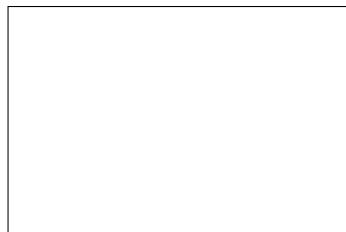
- ▶  $\mathcal{M}$  simulates the remainder of the computation of  $\mathcal{B}$ .
- ▶ If  $\mathcal{B}$  is in an accepting state when the input head of  $\mathcal{M}$  reaches the right border,  $\mathcal{M}$  accepts.

## Example

1.  $C_A$  accepts at bottom,  $C_B$  accepts at right



Input word for  $\mathcal{A}$

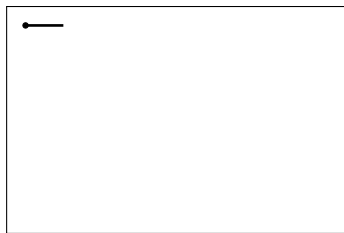


Input word for  $\mathcal{B}$

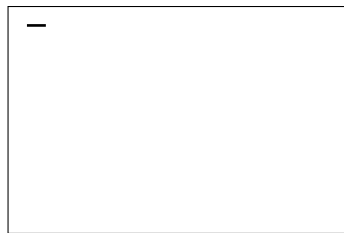
- ▶ First phase, step: (i) (ii) (iii)

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Input word for  $\mathcal{A}$



Input word for  $\mathcal{B}$

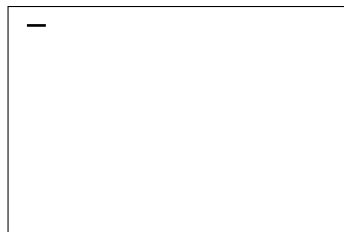
- First phase, step: (i) (ii) **(iii)**

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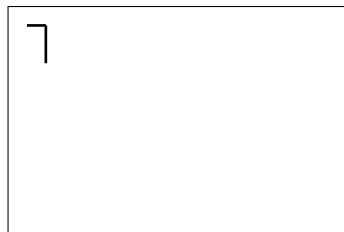
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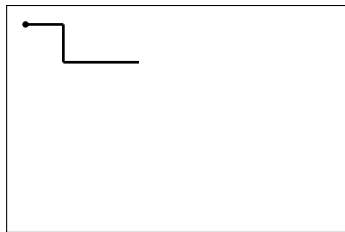


Input word for  $\mathcal{B}$

- ▶ First phase, step: (i) **(ii)** (iii)

## Example

1.  $C_A$  accepts at bottom,  $C_B$  accepts at right



Input word for  $\mathcal{A}$

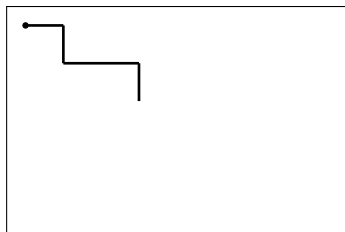


Input word for  $\mathcal{B}$

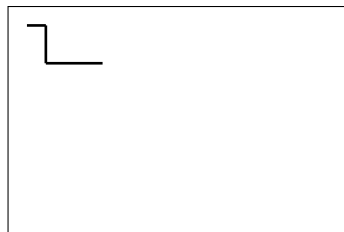
- First phase, step: (i) (ii) **(iii)**

## Example

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Input word for  $\mathcal{A}$

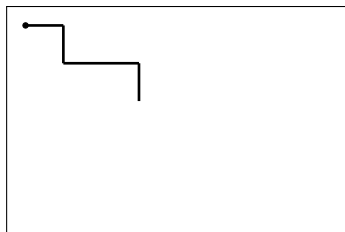


Input word for  $\mathcal{B}$

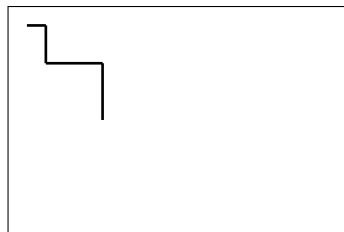
- First phase, step: **(i)** (ii) (iii)

## Example

1.  $C_A$  accepts at bottom,  $C_B$  accepts at right



Input word for  $\mathcal{A}$



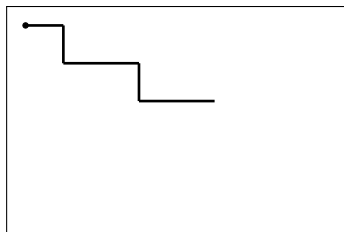
Input word for  $\mathcal{B}$

- First phase, step: (i) **(ii)** (iii)

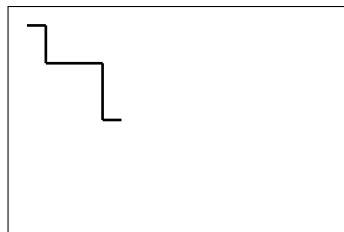


## Example

1.  $C_{\mathcal{A}}$  accepts at bottom,  $C_{\mathcal{B}}$  accepts at right



Input word for  $\mathcal{A}$

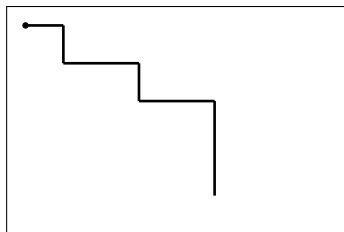


Input word for  $\mathcal{B}$

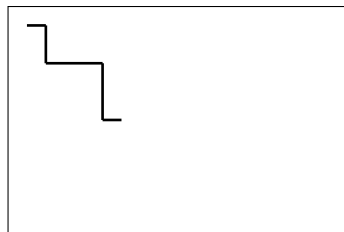
- ▶ First phase, step: (i) (ii) **(iii)**

## Example

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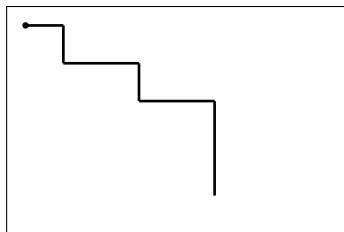


Input word for  $\mathcal{B}$

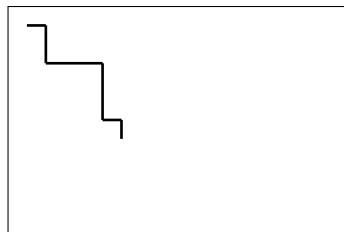
- First phase, step: **(i)** (ii) (iii)

## Example

1.  $C_{\mathcal{A}}$  accepts at bottom,  $C_{\mathcal{B}}$  accepts at right



Input word for  $\mathcal{A}$



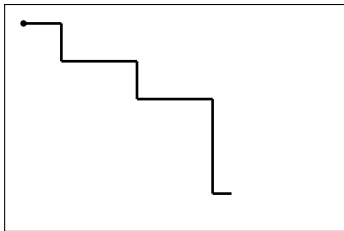
Input word for  $\mathcal{B}$

- First phase, step: (i) **(ii)** (iii)

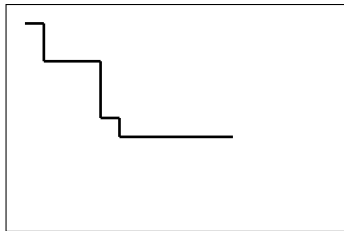
# Unary Row Concatenation: 2NFA-2W

## Example

1.  $C_A$  accepts at bottom,  $C_B$  accepts at right



Input word for  $\mathcal{A}$

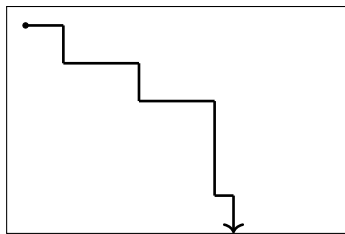


Input word for  $\mathcal{B}$

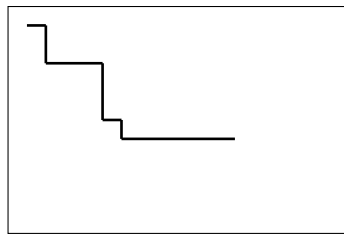
- ▶ First phase, step: (i) (ii) **(iii)**

## Example

1.  $C_{\mathcal{A}}$  accepts at bottom,  $C_{\mathcal{B}}$  accepts at right



Input word for  $\mathcal{A}$

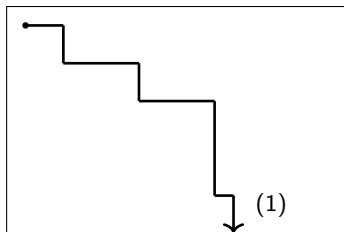


Input word for  $\mathcal{B}$

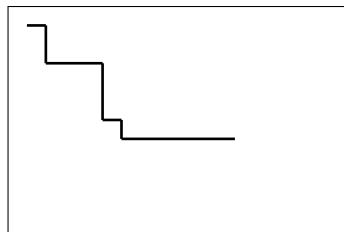
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## Example

1.  $C_A$  accepts at bottom,  $C_B$  accepts at right



Input word for  $\mathcal{A}$

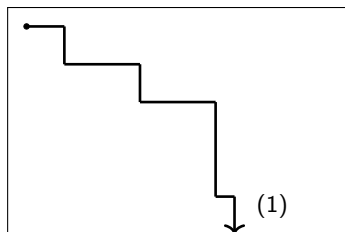


Input word for  $\mathcal{B}$

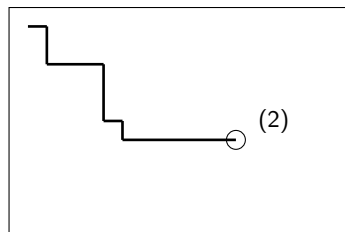
- ▶ First phase, step: **(i)** (ii) (iii)
- ▶ Simulation of  $C_A$  accepts at (1)

## Example

1.  $C_A$  accepts at bottom,  $C_B$  accepts at right



Input word for  $\mathcal{A}$

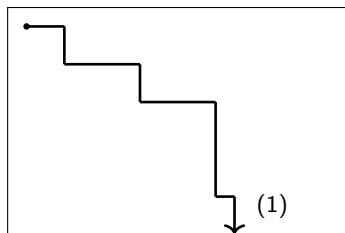


Input word for  $\mathcal{B}$

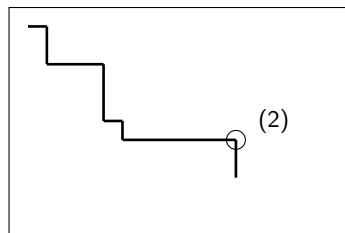
- ▶ First phase, step: **(i)** (ii) (iii)
- ▶ Simulation of  $C_A$  accepts at (1)
- ▶ Computation of  $\mathcal{M}$  begins second phase at (2)

## Example

1.  $C_A$  accepts at bottom,  $C_B$  accepts at right



Input word for  $\mathcal{A}$



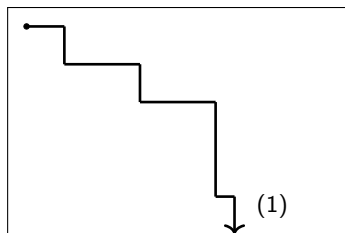
Input word for  $\mathcal{B}$

- ▶ Second phase
- ▶ Simulation of  $C_A$  accepts at (1)
- ▶ Computation of  $\mathcal{M}$  begins second phase at (2)

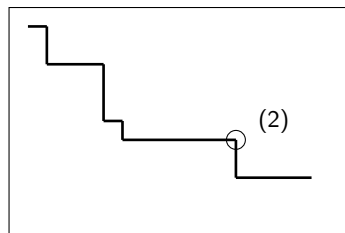


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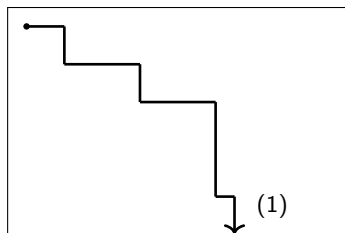


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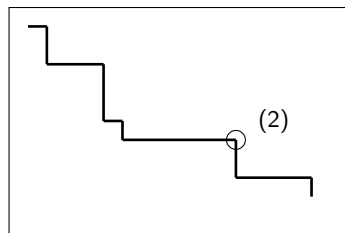
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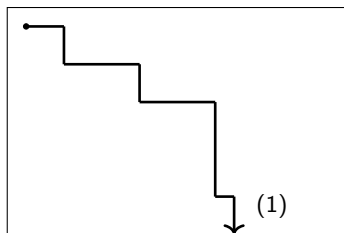


Input word for  $\mathcal{B}$

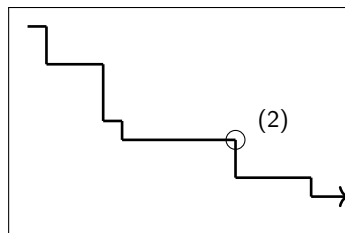
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Input word for  $\mathcal{B}$

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## Theorem

The class 2NFA-2W over a unary alphabet is closed under row concatenation.

- ▶ By swapping downward and rightward moves, we get. . .

## Corollary

The class 2NFA-2W over a unary alphabet is closed under column concatenation.

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The class 2NFA-2W is closed under diagonal concatenation.

## Proof (not in paper)

Construct an automaton  $\mathcal{C}$  that simulates the computations of both original automata  $\mathcal{A}$  and  $\mathcal{B}$ .

Some modifications:

- ▶ Convert first automaton  $\mathcal{A}$  to be IBR-accepting.
- ▶ Modify transition function so that  $\mathcal{C}$  accepts if and only if IBR-accepting  $\mathcal{A}$  would accept on boundary marker.
- ▶ Move input head of  $\mathcal{C}$  some **nondeterministically-selected** number of cells before simulating  $\mathcal{B}$ .

## Theorem

The class 2NFA-2W is closed under diagonal concatenation.

- ▶ As a consequence of the construction, we get. . .

## Theorem

The class 2DFA-2W is not closed under diagonal concatenation.

- ▶ We did not have closure for the class 2DFA-2W.
- ▶ We can reasonably assume that the class 2DFA-3W will also not be closed.
- ▶ However, we require a different approach:
  - ▶ Need to account for added direction of movement
  - ▶ The input head can now read all symbols in a row



## Theorem

The class 2DFA-3W is not closed under diagonal concatenation.

## Key Observations

- ▶ Using a two-way 1D automaton  $\mathcal{N}$ , we can simulate the computation of a three-way 2D automaton  $\mathcal{M}$  on a certain row of its input.
- ▶ The number of states of  $\mathcal{N}$  depends linearly on the number of states of  $\mathcal{M}$ .

- ▶ Let  $\Sigma = \{0, 1\}$ , and let  $\mathcal{M}$  be a deterministic three-way 2D automaton with  $n$  states.
- ▶ To prove our result, we need two lemmas that use  $\mathcal{M}$ .

## First Lemma

Consider the computation of  $\mathcal{M}$  on a row of all-0s.

If the input head of  $\mathcal{M}$  reads the first or last symbol of the row, then it moves downward to the next row at most  $n + 1$  cells away from a boundary marker.

	1	2	$\dots$	$n-1$	$n$	$n+1$	$n+2$	$\dots$
#	0	0	$\dots$	0	①	0	①	$\rightarrow$
					$\downarrow$			
#	1	0	$\dots$	0	1	1	0	

- ▶ Let  $\Sigma = \{0, 1\}$ , and let  $\mathcal{M}$  be a deterministic three-way 2D automaton with  $n$  states.
- ▶ To prove our result, we need two lemmas that use  $\mathcal{M}$ .

## Second Lemma

Suppose  $\mathcal{M}$  enters a row at most  $n + 1$  cells away from a boundary marker. Then there exists a two-way 1D automaton  $\mathcal{N}$  with at most  $2n + 3$  states that

1. simulates the computation of  $\mathcal{M}$  on that row, and
2. accepts if and only if the input head of  $\mathcal{M}$  moves downward to the next row.

- ▶ Kapoutsis (2005) showed that we can take a deterministic two-way 1D automaton with  $n$  states and convert it to a one-way automaton with  $h(n) = n(n^n - (n - 1)^n)$  states.
- ▶ We use this value to construct a “diagonal concatenation” language of words of a certain size, where each row contains certain patterns of symbols.

## Proof Sketch

Using our lemmas, reach a contradiction:

- ▶ Start with a three-way 2D automaton  $\mathcal{C}$  with  $n$  states
- ▶ Convert to a two-way 1D automaton  $\mathcal{D}$  with  $2n + 3$  states
- ▶ Convert to a one-way 1D automaton  $\mathcal{D}'$  with  $h(2n + 3)$  states
- ▶ Problem:  $\mathcal{D}'$  becomes incapable of recognizing rows of words accepted by  $\mathcal{C}$ !

## Introduction

- Two-Dimensional Automata
- Restricted 2D Automata
- Concatenation Operations

## Row/Column Concatenation

- Two-Way 2D Automata
- Unary Two-Way 2D Automata

## Diagonal Concatenation

- Two-Way 2D Automata
- Three-Way 2D Automata

## Conclusions

- ▶ 2D automata can be restricted to move in fewer than four directions.
- ▶ Depending on the model, two concatenated words from some class of languages may or may not belong to that same class.
- ▶ Neither row nor column concatenation is closed for two-way 2D automata...
  - ▶ ...except in the unary nondeterministic case.
- ▶ Diagonal concatenation is closed for nondeterministic two-way 2D automata...
  - ▶ ...but not in the deterministic two-way or deterministic three-way cases.

- ▶ What kind of closure results can we get for other models in the unary case?
- ▶ Do we have closure for diagonal concatenation on four-way 2D automata?
- ▶ Do we have closure for diagonal concatenation on nondeterministic three-way 2D automata?
  - ▶ Conjecture: no, but we require essentially a different approach.

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